# Xingyu SONG

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## **Education and Employment**

2024.05 – Present Research Assistant / Researcher, The University of Tokyo
Graduate School of Engineering / Information Technology Center

2022.04 – 2024.03 M.Eng., The University of Tokyo Graduate School of Engineering

2021.10 – 2022.03 Research Student, Waseda University
School of Fundamental Science and Engineering

2017.09 – 2021.07 **B.Sc., Chongqing University**College of Computer Science

# **Publication and Manuscript**

### **Peer-reviewed Conference**

- Xingyu Song, Z. Li, S. Chen, X.-Q. Cai, and K. Demachi, An animation-based augmentation approach for action recognition from discontinuous video, In: Proceedings of the 27th European Conference on Artificial Intelligence (ECAI'24), Santiago de Compostela, Spain, Oct. 19-24, 2024 (Oral). .
- Xingyu Song, Z. Li, S. Chen, and K. Demachi, Quater-gcn: Enhancing 3d human pose estimation with orientation and semi-supervised training, In: Proceedings of the 27th European Conference on Artificial Intelligence (ECAI'24), Santiago de Compostela, Spain, Oct. 19-24, 2024 (Oral). .
- Xingyu Song, Z. Li, S. Chen, and K. Demachi, Game engine based data augmentation with in-game customization and modeling for malicious behaviors identification in nuclear security, In: Proceedings of the INMM/ESARDA 2023 Joint Annual Meeting, Vienna, Austria, May 22-26, 2023 (Oral). .
- Z. Li, Xingyu Song, S. Chen, and K. Demachi, Malicious behaviors identification in nuclear security based on visual relationships extraction and knowledge reasoning, In: Proceedings of the INMM/ESARDA 2023 Joint Annual Meeting, Vienna, Austria, May 22-26, 2023 (Oral). .

### Journal Article

- L. Zhan, **Xingyu, Song**, C. Shi, and D. Kazuyuki, "Data, language and graph-based reasoning methods for identification of human malicious behaviors in nuclear security," *Expert Systems with Applications*, vol. 236, p. 121 367, 2024. §.
- L. Zhan, **Xingyu, Song**, C. Shi, and D. Kazuyuki, "Armed boundary sabotage: A case study of human malicious behaviors identification with computer vision and explainable reasoning methods," *Computers and Electrical Engineering*, vol. 121, p. 109 924, 2025, ISSN: 0045-7906.

### **Preprint**

1 Xingyu Song, Z. Li, S. Chen, and K. Demachi, Gtautoact: An automatic datasets generation framework based on game engine redevelopment for action recognition, 2024. .

L. Zhan, Xingyu, Song, C. Shi, and D. Kazuyuki, Advancement and development of graph-based reasoning method for human malicious behaviors identification based on graph contrastive representation learning, 2024. S.

#### **Presentation**

- Xingyu Song, Z. Li, S. Chen, and K. Demachi, Real-time Malicious Behaviors Identification for Nuclear Facilities using Vision-based Object Detection and Pose Estimation. INMMJ 43rd Annual Meeting, 2022.
- **Xingyu Song**, Z. Li, S. Chen, and K. Demachi, Game Engine Based Data Augmentation for Malicious Behaviors Identification in Nuclear Security. 2023 Annual Meeting of AESJ, 2023.

### **Award and Achievement**

2024 SPRING GX Fellowship, The University of Tokyo

### Internship

2020.06 – 2020.08 Sichuan Hwadee Information Technology Co., Ltd, Chengdu, China
Development of the big data information integration analysis platform

National key laboratory of Software Development Environment, Beihang University, Beijing, China

Data standard modeling and environment verification Supervised by Prof. Zhiming Zheng

2018.07 – 2018.09 ChinaSoft International, Chongqing, China
Development of the campus forum CQUHub

### **On-going Project**

### ■ Graph + CV

**Topic:** Graph Embedding in Computer Vision

Cooperator: Dr. Xin-Qiang Cai (RIKEN AIP / Sugiyama Lab, UTokyo), Boming Yang (Matsuo Lab,

UTokyo)

Targeting: ICCV2025

#### LLM + GNN

Topic: External Knowledge Understanding by Graph Representation for LLM

**Cooperator:** Dr. Irene Li (Information Technology Center, Utokyo), Yunjie He (Analytical Computing Department, the University of Stuttgart / Bosch Center for Artificial Intelligence), Zixuan He (Demachi Lab, Utokyo)

Targeting: Neurips2025

#### Robotics + HCI

Topic: Human Motion Reconstruction Integrating Deep Learning with Wearable Equipment

**Cooperator:** Fan Yang (IMPE Lab, UTokyo)

Targeting: ICRA2026/CHI2026